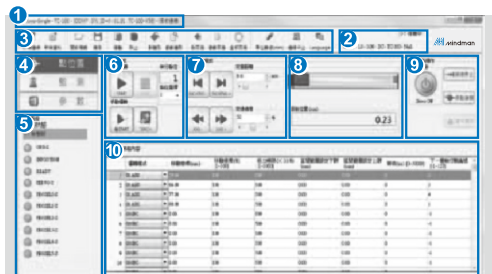


■ Main page-position points



① Basic status bar

Display current system status, from left to right, product name, software name, communication port, station ID, firmware version, software version and connection status.

② Model and controller status

Display current robot model and controller status.

③ Toolbar

The toolbar contains: new connection, new data file, open data file, save, copy, paste, read position point list, read parameters, overwrite position point list, overwrite parameter, overwrite all, display unit change and disconnect.

④ Function page selection

To select the setting of position points, monitoring and parameters.

⑤ Output monitoring

Display current output from controller and alarm status.

⑥ Automatic operation

Proceed with the selected position points automatically.

Operating point

Display current position point.

Manual operation

Proceed with the selected position points automatically.(suggest to use when confirming the teaching).

⑦ Manual operation

Proceed with JOGGING and INCHING.

⑧ Current position

Display the current position.

Simulation display

Simulate the movement of current hardware.

⑨ SERVO/ORG control

Control servo ON or OFF, returning to the ORG, deceleration, stop and alarm reset.

⑩ Position point list

Set position point moving mode, speed, torque, dwell time and next step.

Basic specification

Specification	O/S
OS	Microsoft Windows 2000/XP/Vista/7/8.1
CPU	Meet the requirement of the O/S
Memory	Meet the requirement of the O/S
Free HD space	20MB or above free space
Communication ports	RS485, USB
compatible controller	TC100

■ Monitoring page



① Input monitoring

Monitoring all input signal and all signal is forced to output.

② Output monitoring

Monitoring all output signal but cannot be forced to output to other device.

③ Position and pushing position control

Torque limit movement control.

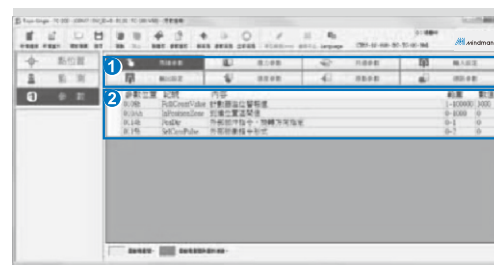
④ Motor status monitoring

Monitoring the motor status, such as current, rotation speed, current position and alarm status...etc.

⑤ Alarm log

Display the last 50 alarm, the latest one is on top.

■ Parameters page



① List of parameters

- Parameters of motor
- Parameters of thrust
- Common parameters
- Setting of input
- Setting of output
- Speed parameters
- Parameters of homing
- Parameters of communication setting

② Parameter content

The content is including the name, description and the of parameters, description and setting value of parameters.